Earth Science Applications of Space Based Geodesy DES-7355 Tu-Th 9:40-11:05

Seminar Room in 3892 Central Ave. (Long building)

Bob Smalley Office: 3892 Central Ave, Room 103 678-4929 Office Hours – Wed 14:00-16:00 or if I'm in my office.

http://www.ceri.memphis.edu/people/smalley/ESCI7355/ESCI_7355_Applications_of_Space_Based_Geodesy.html

Class 5

GPS Signals

GPS signals are broadcast on 2 L-band carriers

L1: 1575.42 MHz Modulated by C/A-code & P-code (codes covered later)

L2: 1227.6 MHz Modulated by P-code only

(3rd carrier, L3, used for nuclear explosion detection)

A. Ganse, U. Washington , http://staff.washington.edu/aganse/ See http://en.wikipedia.org/wiki/Radio_spectrum for electromagnetic frequency band names



Signal: Electromagnetic Spectrum





GPS Signals

Most "unsophisticated" receivers only track L1

If L2 tracked, then the phase difference (L1-L2) can be used to filter out *ionospheric delay*.

This is true even if the receiver cannot decrypt the *Pcode* (more later)

L1-only receivers use a simplified ionospheric correction model

For Signal-Heads Only

Antenna Polarization: RHCP

Center Frequency: 1.57542 GHz

Signal Strength: ~160 dBW Main Lobe Bandwidth: 2.046 MHz C/A & P-Codes in Phase Quadrature

A. Ganse, U. Washington , http://staff.washington.edu/aganse/ http://en.wikipedia.org/wiki/Circular_polarization

For Signal-Heads Only

L2

Center Frequency: 1.22760 GHZ Signal Strength: ~166 dBW Code modulation is Binary, Biphase or Bipolar Phase Shift Key (BPSK)

Total SV Transmitted RF Power ~45 W





- L-band carrier frequency was a compromise
 - At higher frequencies, ranging errors due to ionospheric effects reduce, but attenuation of signal power due to distance traveled increases
- GPS was first wide-spread use of spread spectrum technology
 - Code division multiple access (CDMA)
 - Allows multiple transmitters to use same frequency band
 - Adding code has the effect of "spreading" the signal
 - 2MHz (20MHz) band about the carrier at L₁ ~ 1575.42MHz





Direct Sequence Spread Spectrum



Fig 2: Generation of a DSSS Signal



Fig 3: Spectrum of a DSSS Signal

http://www.ieee.org/organizations/history_center/cht_papers/SpreadSpectrum.pdf

Frequency Hopped Spread Spectrum



Fig 5: Spectrum of a FHSS Signal



GPS signal strength - frequency domain



Note that C/A code is below noise level; signal is multiplied in the receiver by the internally calculated code to allow tracking. C/A-code chip is 1.023 Mhz, P-code chip is 10.23 Mhz

GPS signal strength - frequency domain



$$Power = P(t) = y^2(t)$$

Bandwidth $\equiv B \approx \frac{1}{T}$ where $T \equiv$ is chip duration

GPS signal strength - frequency domain



The calculated power spectrum derives from the Fourier transform of a square wave of width 21 and unit amplitude.

FD shape common function in DSP called the "sinc" function.

PRN Codes

GPS signals implement PseudoRandom Noise Codes Enables very low power (below background noise) A form of direct-sequence spread-spectrum Specifically a form of Code Division Multiple Access (CDMA), which permits frequency sharing Pseudo random numbers/sequences What are they? Deterministic but "look" random Example – digits of π

3.14159265358979323846264338327950288419716939937510

Looks like a random sequence of single digit numbers. But you can compute it. Is perfectly deterministic. Frequency of individual digits (first 10,000 digits) This list excludes the 3 before the decimal point

Digit	Frequency
0	968
1	1026
2	1021
3	974
4	1012
5	1046
6	1021
7	970
8	948
9	1014
Total	10000

http://www.ex.ac.uk/cimt/general/pi10000.htm

PRN Codes

Codes are known "noise-like" sequences Each bit (0/1) in the sequence is called a *chip* Each GPS SV has an assigned code Receiver generates equivalent sequences internally and matches signal to identify each SV There are currently 32 reserved PRN's (so max 32 satellites)

PRN Code matching

Receiver slews internally-generated code sequence until full "match" is achieved with received code

Time data in the nav message tells receiver when the transmitted code went out

Slew time = time delay incurred by SV-to-receiver range Minus clock bias and whole cycle ambiguities

Receiver/Signal Code Comparison



Coarse Acquisition (C/A) Code

1023-bit Gold Code

Originally intended as simply an acquisition code for *P*code receivers

Modulates LI only

Chipping rate = 1.023 MHz (290 meter "wavelength")

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Coarse Acquisition (C/A) Code

Sequence Length = 1023 bits, thus Period = 1 millisec

~300 km range ambiguity: receiver must know range to better than this for position solution

Provides the data for *Standard Positioning Service* (SPS)

The usual position generated for most civilian receivers

Modulated by the Navigation/Timing Message code

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Precise (P) Code

P code is known, but encrypted by unknown (secret) W code into the Y-code

Requires special chip to decode Modulates both L1 & L2 Also modulated by Nav/Time data message Chipping rate = 10.23 MHz

Precise (P) Code

Sequence Length (Y code?) = BIG (Period = 267 days)

Actually the sum of 2 sequences, X1 & X2, with subperiod of 1 week

Precise (P) Code

P-code rate is the fundamental frequency (provides the basis for all others)

P-Code (10.23 MHz) / 10 = 1.023 MHz (C/A code)

 $P-Code (10.23 \text{ MHz}) \times 154 = 1575.42 \text{ MHz} (L1).$

 $P-Code (10.23 \text{ MHz}) \times 120 = 1227.60 \text{ MHz} (L2).$

Code Modulation



Image courtesy: Peter Dana, http://www.colorado.Edu/geography/gcraft/notes/gps/gps_f.html

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DGPS overview, www.edu-observatory.org/gps/BostonSection.ppt, Dierendonck

Why Modernize? National policy - GPS is a vital dual-use system For civil users, new signals/frequencies provide: More robustness against interference, compensation for ionospheric delays and wide/tri-laning For military users, new signals provide: Enhanced ability to deny hostile GPS use, greater military anti-jam capability and greater security For both civil/military, system improvements in accuracy, reliability, integrity, and availability

DGPS overview, www.edu-observatory.org/gps/BostonSection.ppt, Dierendonck

generation of code - satellite and receiver

Time Seconds 0123456789012345678901234567890123456789012345678901234567890123456 (Genesis - sent by satellite 1 and generated in receiver) In the beginning God created the heavens and thIn the beg (Exodus - sent by satellite 2 and generated in receiver) These are the names of the sons of Israel who wIhese are (Leviticus - sent by satellite 3 and generated in receiver) Yahweh called Moses, and from the Tent of MeetiYahweh code (repeats)

Reception of code in receiver

The time of the reception of the code is found by lining up the known and received signals Time Seconds

> In the beginning God created the heavens an ^14 seconds

These are the names of the sons of Israel who wThese ^5 seconds

> Yahweh called Moses, and from the T ^22 seconds





GPS Signals (Code)

- Coarse/Acquisition (C/A) codes enable:
 - Simultaneous measurements from many satellites (CDMA)
 - Accurate absolute range (10-100m) using signal propagation delay



- Each satellite has a unique C/A code
 - One of a repeating sequence 1023 chips long
 - Rate of 1.023MHz (period of 1ms)
 - Appear random (pseudo random PRN), but one of the deterministic "Gold Codes"





- Receiver replicates the C/A code to correlate with the measured signal
- What is correlation? • Mathematics: $\Psi_{ij}(\tau) = \frac{1}{T} \int_0^T \left[c_i(t \nabla_i t - \tau) \right] dt$
- Receiver slides code replice (τ) until strong correlation found with transmitted signal

→ Correlation ≈ (# Agree - # Differ)/N

- Comparison with wrong code will produce very low agreement for all τ
 - Right code, wrong τ also produces low agreement



Correlation Visualization



From J. HOW, MIT



GPS Signal Processing

- Correlation:
 - Allows receiver to pick up the very weak signal
 - Allows us to determine the time offset of the incoming signal
 - → Transit Time
- Transit time will be off _ by the user clock error, but we can solve for & remove that term



Measuring Distance





GPS Signal Acquisition Process

- Determine which satellites are visible
 - Approximate time/position, GPS almanac → skyplot
- Determine approximate Doppler for each satellite
 - Reduces time-to-first-fix since defines frequency search space (estimate of receiver clock drift required)
- Must search both frequency and C/A code phase
 - Large velocity of GPS satellites, so the received signals can have a large Doppler shift (+/- 5 KHz) that can vary rapidly
 - Accurate frequency knowledge required to "strip off" the carrier part of the signal
 - Estimate frequency range to search using Doppler shift
 - Search frequency range using ~20 frequency bins of 500 Hz

if receiver applies different PRN code to SV signalno correlation



when receiver uses same code as SV and codes begin to align ...some signal power detected



when receiver and SV codes align completelyfull signal power detected



Full Correlation (Code-Phase Lock) of Receiver and Satellite PRN Codes

usually a late version of code is compared with early version to insure that correlation peak is tracked

Mattioli-http://comp.uark.edu/~mattioli/geol_4733.html and Dana

PRN Cross-correlation Correlation of receiver generated PRN code (A) with incoming data stream consisting of multiple (e.g. four, A, B, C, and D) codes







Rinder and Bertelsen, kom.aau.dk/~rinder/AAU_software_receiver.pdf

Construction of LI signal BPSK modulation (Carrier) x (C/A code) x (navigation message) = LI signal



Rinder and Bertelsen, kom.aau.dk/~rinder/AAU_software_receiver.pdf

Digital Modulation Methods

Amplitude Modulation (AM) also known as amplitudeshift keying. This method requires changing the amplitude of the carrier phase between 0 and 1 to encode the digital signal.

Digital Modulation Methods

Frequency Modulation (FM) also known as frequencyshift keying. Must alter the frequency of the carrier to correspond to 0 or 1.

Digital Modulation Methods

Phase Modulation (PM) also known as phase-shift keying. At each phase shift, the bit is flipped from 0 to 1 or vice versa. This is the method used in GPS.

Modulation Schematics



Nearly no cross-correlation.

C/A codes nearly uncorrelated with one another.

$$R_{ik}(n) = \sum_{l=0}^{1022} c^{i}(l) c^{k}(l+n) \approx 0, \ \forall n, i \neq k$$

Nearly no auto-correlation, except for zero lag C/A codes nearly uncorrelated with themselves, except for zero lag.

$$R_{kk}(n) = \sum_{l=0}^{1022} c^{k}(l) c^{k}(l+n) \approx 0, \ \forall |n| \ge 0$$

Rinder and Bertelsen, kom.aau.dk/~rinder/AAU_software_receiver.pdf

Gold Code correlation properties

Auto-correlation with itself (narrow peak, 1023)

Cross-correlation with another code



Signal acquisition Is a search procedure over correlation by frequency and code phase shift



kom.aau.dk/~rinder/AAU_software_receiver.pdf

Rinder and Bertelsen, kom.aau.dk/~rinder/AAU_software_receiver.pdf

Search resulting grid of correlations for maximum, if above some threshold signal has been detected at some frequency and phase shift.



kom.aau.dk/~rinder/AAU_software_receiver.pdf

Rinder and Bertelsen, kom.aau.dk/~rinder/AAU_software_receiver.pdf

49

Search resulting grid of correlations for maximum, if it is small everywhere, below threshold, no signal has been detected.



Rinder and Bertelsen, kom.aau.dk/~rinder/AAU_software_receiver.pdf

This method,

while correct and useful for illustration,

is too slow for practical use



Rinder and Bertelsen, kom.aau.dk/~rinder/AAU_software_receiver.pdf

Recovering the signal

Fourier analysis of this indicates the presence of the signal and identifies the frequency



Rinder and Bertelsen, kom.aau.dk/~rinder/AAU_software_receiver.pdf

Additional information included in GPS signal Navigation Message

In order to solve the user position equations, one must know where the SV is.

The navigation and time code provides this 50 Hz signal modulated on L1 and L2

Navigation Message

The SV's own position information is transmitted in a 1500-bit data frame (broadcast orbits) Pseudo-Keplerian orbital elements, fit to 2-hour spans Determined by control center via ground tracking Receiver implements orbit-to-position algorithm

Navigation Message

Also includes clock data and satellite status And ionospheric/tropospheric corrections

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Additional information on GPS signal The Almanac

In addition to its own nav data, each SV also broadcasts info about ALL the other SV's

In a reduced-accuracy format

Known as the Almanac

The Almanac

Permits receiver to predict, from a cold start, "where to look" for SV's when powered up

GPS orbits are so predictable, an almanac may be valid for months

Almanac data is large

12.5 minutes to transfer in entirety

Selective Availability (SA)

To deny high-accuracy realtime positioning to potential enemies, DoD reserves the right to deliberately degrade GPS performance

Only on the C/A code

By far the largest GPS error source

Selective Availability (SA)

Accomplished by:

1) "Dithering" the clock data
Results in erroneous pseudoranges

2) Truncating the navigation message data Erroneous SV positions used to compute position

Selective Availability (SA)

Degrades SPS solution by a factor of 4 or more Long-term averaging only effective SA compensator FAA and Coast Guard pressured DoD to eliminate ONIMAY 2000: SA WAS DISABLED BY PRESIDENTAL DIRECTIVE

How Accurate Is GPS?

Remember the 3 types of Lies: Lies, Damn Lies, and Statistics...

Loosely Defined "2-Sigma" Repeatable Accuracies: All depend on receiver quality How Accurate Is GPS?

SPS (C/A Code Only)

S/A On: Horízontal: 100 meters radíal Vertícal: 156 meters Tíme: 340 nanoseconds

S/A Off: Horízontal: 22 meters radíal Vertícal: 28 meters Tíme: 200 nanoseconds



SA Transition -- 2 May 2000



Position averages



5.5 hours S/A on 8 hours S/A off Note scale difference How Accurate Is It?

PPS (P-Code)

Slightly better than C/A Code w/o S/A (?)

Differential GPS

A reference station at a known location compares predicted pseudoranges to actual & broadcasts corrections: "Local Area" DGPS (LAAS)

Broadcast usually done on FM channel

Corrections only valid within a finite range of base User receiver must see same SV's as reference.

USCG has a number of DGPS stations operating (CORS network)

Differential GPS

Base stations worldwide collect pseudorange and SV ephemeris data and "solve-for" time and nav errors

Available conterminous US Not yet globally available

DGPS can reduce errors to < 10 meters





WAAS

Wide Area Augmentation System

is a satellite navigation system consisting of equipment and software which augment the GPS Standard Positioning Service (SPS).